## DIFFERENTIAL MANIFOLDS HOMEWORK 2

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## 1. Exercise 1.20

(a). Suppose X is star shaped about  $x_0$ . Then our homotopy is naturally  $F(t, x) := tx + (1 - t)x_0, x \in X$  and  $t \in [0, 1]$ . By definition of star shaped, this segment must lie within X.

(b). Setting  $x_0 = 0$  in the above homotopy formula, we have that F(t, x) = tx. Now consider a *p*-form  $\omega$ . First compute  $F^*\omega$ :

(1.1)  

$$F^*\omega_{(s,x)}((\delta s, \delta x), (\delta' s, \delta' x)) = \omega_{sx}(\delta(sx), \delta'(sx))$$

$$= \omega_{sx}(x\delta s + s\delta x, x\delta' s + s\delta' x)$$

Where  $\delta s$ ,  $\delta x$  are tangent vectors at (s, t). Now take the interior product with V(s, x) = (1, 0):

(1.2)  

$$i_V \omega_{sx}(x\delta s + s\delta x, x\delta' s + s\delta' x) = \omega_{sx}(x\delta s(1,0) + s\delta x(1,0), x\delta' s + s\delta' x)$$
  
 $= \omega_{sx}(x, s\delta x) + \omega_{sx}(x, x\delta s)$   
 $= \omega_{sx}(x, \delta x)s$ 

Now consider the pullback of  $G := e^{tV} \circ J$  which takes  $x \mapsto (t, x)$ . Then this is merely the change of variable sending  $s \mapsto t$ . To see this, merely rewrite:

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$$=\omega_{sx}(x, \ \delta x)s = \omega_{F(s,t)}(\delta F(s,x)(1,0), \delta' F(s,x))$$

Then our pullback becomes:

(1.3)  

$$[e^{tV} \circ J]^* \omega_{F(s,t)}(\delta F(s,x)(1,0), \delta' F(s,x)) = \omega_{F(G(x))}(\delta F(G(x))(1,0), \delta' F(G(x)))$$

$$= \omega_{tx}(x, \ \delta x)t$$

Finally, integrating from 0 to 1:

$$H\omega(\delta x) = \int_0^1 \omega_{tx}(x, \ \delta x) t dt$$

And for a constant form,  $\omega_{tx} = \omega$  so that

$$H\omega(\delta x) = \omega(x, \ \delta x) \int_0^1 t dt = \frac{1}{2}\omega(x, \ \delta x)$$

(c). Consider the case for any p-form  $\omega$ . Our pullback  $F^*$  becomes:

(1.4)  

$$F^*\omega\Big((\delta^1 x, \delta^1 x), \ldots, \delta^p s, \delta^p x)\Big) = \omega_{sx}\big(\delta^1(sx), \ldots, \delta^p(sx)\big)$$

$$= \omega_{sx}\big(s\delta^1 x + x\delta^1 s, \ldots, s\delta^p x + x\delta^p s\big)$$

And computing the interior product similarly:

$$(1.5)$$

$$i_V \omega_{sx} (s\delta^1 x + x\delta^1 s, \dots, s\delta^p x + x\delta^p s) = \omega_{sx} (s\delta^1 x(1,0) + x\delta^1 s(1,0), \dots, s\delta^p x + x\delta^p s)$$

$$= \omega_{sx} (x, \dots, s\delta^p x + x\delta^p s)$$

$$= \omega_{sx} (x, \delta^2 x, \dots, \delta^p x) s^{p-1}$$

Arguing identically as in part (b), the pullback by  $e^{tV} \circ J$  merely sends  $s \mapsto t$ , so we derive the general case:

$$H\omega(\delta^2 x, \ldots, \delta^p x) = \int_0^1 \omega_{tx}(x, \ \delta^2 x, \ \ldots, \ \delta^p x) t^{p-1} dt$$

And for a constant form,

$$H\omega(\delta^2 x, \ \dots, \delta^p x) = \frac{1}{p}\omega(\delta^2 x, \ \dots, \delta^p x)$$

And we are done.

## 2. Problem 1.21

(a). We first check that  $\theta = (2xy + z^2)dx + x^2dy + 2xzdz$  is in fact closed:

$$(2.1)$$

$$d\theta = (2ydx + 2xdy + 2zdz) \wedge dx + (2xdx) \wedge dy + (2zdx + 2xdz) \wedge dz$$

$$= -2xdx \wedge dy + 2zdz \wedge dx + 2xdx \wedge dy - 2zdz \wedge dx$$

$$= 0$$

So that  $\theta$  is closed. Now, using the formula from 1.20, we know:

 $\mathrm{d}H\omega=\omega$ 

Where  $H\omega = \int_0^1 \omega_{tx}(\delta x) dt$ . Then, in our case we see the triple  $(x, y, z) \mapsto (tx, ty, tz)$  and  $(dx, dy, dz) \mapsto (x, y, z)$  (this works because evaluating our one forms merely results a replacement). Using this,  $\theta$  is mapped to the 0-form:

$$\theta \mapsto t^2(2xy+z^2)x+t^2x^2y+t^22xz^2$$

And integrating from 0 to 1, we find our antiderivative:

$$H\theta = x^2y + xz^2$$

(b). Again, we check that  $\omega = (x^2 - 2xy)dy \wedge dz + (y^2 - 2yz)dz \wedge dx + (z^2 - 2zx)dx \wedge dy$  is closed:

$$(2.2)$$
  

$$d\omega = (2xdx - 2ydx - 2xdy) \wedge dy \wedge dz$$
  

$$+ (2ydy - 2zdy - 2ydz) \wedge dz \wedge dx$$
  

$$+ (2zdz - 2zdx - 2xdz) \wedge dx \wedge dy$$
  

$$= (2x - 2y)dx \wedge dy \wedge dz + (2y - 2z)dy \wedge dz \wedge dx + (2z - 2x)dz \wedge dx \wedge dy$$
  

$$= (2x - 2y + 2y - 2z + 2z - 2x)dx \wedge dy \wedge dz = 0$$

So  $\omega$  is exact. Now, using the derived formula from 1.20 again,  $(x, y, z) \mapsto (tx, ty, tz)$  and we evaluate our vector fields at each of x, yand z. The final result becomes

$$H\omega = \frac{yz(2x+y-3z)}{4}dx - \frac{xz(3x-2y-z)}{4}dy + \frac{xy(x-3y+2z)}{4}dz$$

And this is an antiderivative (note that this is not unique! We can find a simpler antiderivative just by inspection).

## 3. Exercise 1.22

Compute the pullback of  $F(\rho, \phi)$  as recommended in the hint. We see that  $x = \rho \cos \phi$ ,  $y = \rho \sin \phi$ , and

$$dx = \cos \phi d\rho - \rho \sin \phi d\phi$$
$$dy = \sin \phi d\rho + \rho \cos \phi d\phi$$

Plugging in,

(3.1)  

$$F^*\omega = \rho^{-2}(\rho\sin\phi\cos\phi d\rho + \rho^2\cos^2\phi\phi d\phi) - \rho^{-2}(\rho\sin\phi\cos\phi d\rho - \rho^2\sin^2\phi d\phi)$$

$$= \rho^{-2}(\rho^2(\cos^2\phi + \sin^2\phi))d\phi = d\phi$$

This shows that  $\omega$  is closed automatically since  $dd\phi = 0$ .

Now, note that this would imply that  $\phi = \phi(x, y)$  is our antiderivative. Hence, as  $\phi \to \pi$ , we see that  $\phi(x, y) \to \phi(-1, 0) = \pi$ , and likewise as  $\phi \to -\pi$ ,  $\phi(x, y) \to \phi(-1, 0) = -\pi$ . But this is impossible, as  $\phi(-1, 0)$  now takes on two different values.